

Module-01 [Question Bank]

① find the angle between normal to the surface $xy = z^2$ at the points $(4, 1, 2)$ and $(3, 3, -3)$

Given: $\phi = xy - z^2$ — (1)

We know that, the angle b/w two surfaces is the angle b/w the normals of the two surfaces

$$\hat{n} = \frac{\nabla \phi}{|\nabla \phi|}$$

$$\nabla \phi = \frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k}$$

$$\nabla \phi = y \hat{i} + x \hat{j} + (-2z) \hat{k}$$

$$\nabla \phi = y \hat{i} + x \hat{j} - 2z \hat{k}$$

$$\nabla \phi_{(4,1,2)} = \hat{i} + 4\hat{j} - 4\hat{k} \rightarrow (A)$$

$$|\nabla \phi| = \sqrt{1^2 + 4^2 + (-4)^2} = \sqrt{33} \rightarrow |A|$$

similarly at $(3, 3, -3)$

$$\nabla \phi_{(3,3,-3)} = 3\hat{i} + 3\hat{j} + 6\hat{k} \rightarrow (B)$$

$$|\nabla \phi| = \sqrt{3^2 + 3^2 + 6^2} = \sqrt{54} \rightarrow |B|$$

Now, the angle b/w two surface is given that

$$\cos \theta = \frac{\nabla \phi_1 \cdot \nabla \phi_2}{|\nabla \phi_1| |\nabla \phi_2|} \Rightarrow \frac{A \cdot B}{|A| |B|}$$

$$\cos \theta = \frac{(\hat{i} + 4\hat{j} - 4\hat{k}) \cdot (3\hat{i} + 3\hat{j} + 6\hat{k})}{\sqrt{33} \sqrt{54}}$$

$$\cos \theta = \frac{3 + 12 - 24}{9\sqrt{22}} = \frac{-9}{9\sqrt{22}} = \underline{\underline{-\frac{1}{\sqrt{22}}}}$$

② find the angle between surfaces $x^2 + y^2 + z^2 = 9$ and $x^2 + y^2 - 3 = z$ at the point $(2, -1, 2)$

Given: $\phi_1 = x^2 + y^2 + z^2 - 9$

$\phi_2 = x^2 + y^2 - z - 3$

wkt, The angle b/w two surface is $\cos \theta = \frac{\nabla \phi_1 \cdot \nabla \phi_2}{|\nabla \phi_1| |\nabla \phi_2|}$

$$\nabla \phi_1 = 2x\hat{i} + 2y\hat{j} + 2z\hat{k}$$

$$(\nabla \phi_1)_{(2,-1,2)} = 4\hat{i} - 2\hat{j} + 4\hat{k}$$

$$|\nabla \phi_1| = \sqrt{16 + 4 + 16} = \sqrt{36} = 6$$

$$\nabla \phi_2 = 2x\hat{i} + 2y\hat{j} - \hat{k}$$

$$(\nabla \phi_2)_{(2,-1,2)} = 4\hat{i} - 2\hat{j} - \hat{k}$$

$$|\nabla \phi_2| = \sqrt{16 + 4 + 1} = \sqrt{21}$$

$$\cos \theta = \frac{4\hat{i} - 2\hat{j} + 4\hat{k} \cdot 4\hat{i} - 2\hat{j} - \hat{k}}{6\sqrt{21}} = \frac{16 + 4 - 4}{6\sqrt{21}} = \frac{16}{6\sqrt{21}} = \frac{8}{3\sqrt{21}}$$

$$\boxed{\cos \theta = \frac{8}{3\sqrt{21}}}$$

③ If $\vec{F} = \text{grad}(x^3 + y^3 + z^3 - 3xyz)$ find $\text{div} \vec{F}$ and $\text{Curl} \vec{F}$

$$\nabla \phi = \frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k}$$

$$\nabla \phi = (3x^2 - 3yz)\hat{i} + (3y^2 - 3xz)\hat{j} + (3z^2 - 3xy)\hat{k}$$

$$\text{div} \vec{F} = \frac{\partial}{\partial x} (3x^2 - 3yz) + \frac{\partial}{\partial y} (3y^2 - 3xz) + \frac{\partial}{\partial z} (3z^2 - 3xy)$$

$$\text{div} \vec{F} = 6x + 6y + 6z$$

$$\boxed{\text{div} \vec{F} = 6(x + y + z)}$$

$$\text{curl} \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ (3x^2 - 3yz) & (3y^2 - 3xz) & (3z^2 - 3xy) \end{vmatrix}$$

$$= \hat{i} \left(\frac{\partial}{\partial y} (3z^2 - 3xy) - \frac{\partial}{\partial z} (3y^2 - 3xz) \right) - \hat{j} \left(\frac{\partial}{\partial x} (3z^2 - 3xy) - \frac{\partial}{\partial z} (3x^2 - 3yz) \right) + \hat{k} \left(\frac{\partial}{\partial x} (3y^2 - 3xz) - \frac{\partial}{\partial y} (3x^2 - 3yz) \right)$$

$$= \hat{i}(-3x + 3x) - \hat{j}(-3y + 3y) + \hat{k}(-3z + 3z)$$

$$= \underline{\underline{0}}$$

④ If $\vec{F} = \nabla (xy^3z^2)$ find $\text{div} \vec{F}$ and $\text{Curl} \vec{F}$ at the point $(1, -1, 1)$

$$\nabla \phi = \frac{\partial}{\partial x} (xy^3z^2) \hat{i} + \frac{\partial}{\partial y} (xy^3z^2) \hat{j} + \frac{\partial}{\partial z} (xy^3z^2) \hat{k}$$

$$\nabla \phi = (y^3z^2) \hat{i} + (3xy^2z^2) \hat{j} + (2xy^3z) \hat{k}$$

$$\text{div} \vec{F} = \frac{\partial}{\partial x} (y^3z^2) + \frac{\partial}{\partial y} (3xy^2z^2) + \frac{\partial}{\partial z} (2xy^3z)$$

$$= 0 + 6xyz^2 + 2xy^3$$

$$\text{div} \vec{F}_{(1,-1,1)} = 6(-1) + 2(-1) = -6 - 2 = -8$$

$$\text{Curl} \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y^3z^2 & 3xy^2z^2 & 2xy^3z \end{vmatrix}$$

$$= \hat{i} \left(\frac{\partial}{\partial y} (2xy^3z) - \frac{\partial}{\partial z} (3xy^2z^2) \right) - \hat{j} \left(\frac{\partial}{\partial x} (2xy^3z) - \frac{\partial}{\partial z} (y^3z^2) \right) + \hat{k} \left(\frac{\partial}{\partial x} (3xy^2z^2) - \frac{\partial}{\partial y} (y^3z^2) \right)$$

$$= \hat{i} (6xy^2z - 6xy^2z) - \hat{j} (2y^3z - 2y^3z) + \hat{k} (3x^2z^2 - 3x^2z^2)$$

$$\text{Curl} \vec{F} = 0$$

⑤ Find the Directional derivative of $\phi = 4xz^3 - 3x^2y^2z$ at $P(2, -1, 2)$ along $2\hat{i} - 3\hat{j} + 6\hat{k}$.

Given:

$$\phi = 4xz^3 - 3x^2y^2z$$

wkt, Directional Derivative formula

$$D.D = \nabla \phi \cdot \frac{\vec{A}}{|\vec{A}|}$$

$$\text{Now, } \nabla \phi = \frac{\partial}{\partial x} (4xz^3 - 3x^2y^2z) \hat{i} + \frac{\partial}{\partial y} (4xz^3 - 3x^2y^2z) \hat{j} + \frac{\partial}{\partial z} (4xz^3 - 3x^2y^2z) \hat{k}$$

$$= (4z^3 - 6xy^2z) \hat{i} + (-6x^2yz) \hat{j} + (12xz^2 - 3x^2y^2) \hat{k}$$

$$\nabla \phi_{(2,-1,2)} = 32 - 24 \hat{i} + 48 \hat{j} + 96 - 12 \hat{k}$$

$$\nabla \phi_{(2,-1,2)} = 8 \hat{i} + 48 \hat{j} + 84 \hat{k}$$

$$|A| = \sqrt{2^2 + (-3)^2 + 6^2} = \sqrt{4 + 9 + 36} = \sqrt{49} = 7.$$

$$D \cdot D = \frac{8\hat{i} + 48\hat{j} + 84\hat{k} \cdot 2\hat{i} + 3\hat{j} + 6\hat{k}}{7}$$

$$D \cdot D = \frac{16 - 144 + 504}{7} = \boxed{\frac{376}{7}}$$

⑥ Show that $\vec{F} = \frac{x\hat{i} + y\hat{j}}{x^2 + y^2}$ is both solenoidal and irrotational.

$$\text{Given: } \vec{F} = \frac{x\hat{i} + y\hat{j}}{x^2 + y^2} \Rightarrow \frac{x}{x^2 + y^2} \hat{i} + \frac{y}{x^2 + y^2} \hat{j}$$

w.k.T If $\text{Div } \vec{F} = 0$ then it is solenoidal

If $\text{Curl } \vec{F} = 0$ then it is irrotational.

$$\begin{aligned} \text{Div } \vec{F} &= \frac{\partial}{\partial x} \left(\frac{x}{x^2 + y^2} \right) + \frac{\partial}{\partial y} \left(\frac{y}{x^2 + y^2} \right) \quad [\because \text{Applying quotient rule}] \\ &= \frac{x^2 + y^2(1) - x(2x)}{(x^2 + y^2)^2} + \frac{x^2 + y^2(1) - y(2y)}{(x^2 + y^2)^2} \\ &= \frac{x^2 + y^2 - 2x^2}{(x^2 + y^2)^2} + \frac{x^2 + y^2 - 2y^2}{(x^2 + y^2)^2} \end{aligned}$$

$$\text{Div } \vec{F} = \frac{\cancel{2x^2} + \cancel{2y^2} - \cancel{2x^2} - \cancel{2y^2}}{(x^2 + y^2)^2} = 0 \quad \text{Hence it is solenoidal}$$

$$\begin{aligned} \text{Curl } \vec{F} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{x}{x^2 + y^2} & \frac{y}{x^2 + y^2} & 0 \end{vmatrix} \\ &= \hat{i} \left(-\frac{\partial}{\partial z} \left(\frac{y}{x^2 + y^2} \right) \right) - \hat{j} \left(-\frac{\partial}{\partial z} \left(\frac{x}{x^2 + y^2} \right) \right) + \hat{k} \left(\frac{\partial}{\partial x} \left(\frac{y}{x^2 + y^2} \right) - \frac{\partial}{\partial y} \left(\frac{x}{x^2 + y^2} \right) \right) \\ &= \hat{k} \left(\frac{x^2 + y^2(0) - y(2x)}{(x^2 + y^2)^2} - \frac{x^2 + y^2(0) - x(2y)}{(x^2 + y^2)^2} \right) \end{aligned}$$

$$\text{Curl } \vec{F} = \hat{k} \left(\frac{-\cancel{2xy} + \cancel{2xy}}{(x^2 + y^2)^2} \right) = 0 \quad \text{Hence it is irrotational}$$

⑦ find the constants a, b & c such that $\vec{F} = (x+y+az)\hat{i} + (bx+2y-z)\hat{j} + (x+cy+2z)\hat{k}$ is an irrotational.

Given: $\vec{F} = (x+y+az)\hat{i} + (bx+2y-z)\hat{j} + (x+cy+2z)\hat{k}$

WKT $\text{curl } \vec{F} = 0$ then it is irrotational.

$$\begin{aligned} \text{curl } \vec{F} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x+y+az & bx+2y-z & x+cy+2z \end{vmatrix} \\ &= \hat{i} \left(\frac{\partial}{\partial y} (x+cy+2z) - \frac{\partial}{\partial z} (bx+2y-z) \right) - \hat{j} \left(\frac{\partial}{\partial x} (x+cy+2z) - \frac{\partial}{\partial z} (x+y+az) \right) \\ &\quad + \hat{k} \left(\frac{\partial}{\partial x} (bx+2y-z) - \frac{\partial}{\partial y} (x+y+az) \right) \\ &= \hat{i} (c+1) - \hat{j} (1-a) + \hat{k} (b-1) \\ \text{curl } \vec{F} &= \begin{matrix} c+1=0 & 1-a=0 & b-1=0 \\ \boxed{c=-1} & \boxed{a=1} & \boxed{b=1} \end{matrix} \end{aligned}$$

$\therefore$ The constants a, b and c are $1, 1$ & -1 respectively.

⑧ find the directional derivative of $\phi = xy^2 + yz^3$ at $(1, 2, -1)$ in the direction normal to the surface $x \log z - y^2 = -4$ at $(-1, 2, 1)$.

Given: $\phi = xy^2 + yz^3$

$x \log z - y^2 = -4 \Rightarrow f = x \log z - y^2 + 4$

W.K.T, $\nabla \phi = \frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k}$

$\nabla \phi = (y^2)\hat{i} + (2xy+z^3)\hat{j} + (3yz^2)\hat{k}$

$\nabla \phi_{(0,2,-1)} = 4\hat{i} + 3\hat{j} + 6\hat{k}$

$\nabla f = \frac{\partial}{\partial x} (x \log z - y^2 + 4) \hat{i} + \frac{\partial}{\partial y} (x \log z - y^2 + 4) \hat{j} + \frac{\partial}{\partial z} (x \log z - y^2 + 4) \hat{k}$
 $= \log z \hat{i} + (-2y) \hat{j} + \frac{x}{z} \hat{k}$

$\nabla f_{(-1,2,1)} = 0\hat{i} + (-4)\hat{j} + -1\hat{k} \Rightarrow \boxed{-4\hat{j} - \hat{k}}$

Now,

$$D \cdot D = \nabla \phi \cdot \frac{\nabla F}{|\nabla F|}$$

$$D \cdot D = \frac{4\hat{i} + 3\hat{j} + 6\hat{k} \cdot -4\hat{j} - \hat{k}}{\sqrt{16+1}} = \frac{-12-6}{\sqrt{17}} = \frac{-18}{\sqrt{17}}$$

⑩ find the constant 'a' so that $\vec{F} = y(ax^2 + z)\hat{i} + x(y^2 - z^2)\hat{j} + 2xy(z - xy)\hat{k}$ is solenoidal.

Given: $\vec{F} = y(ax^2 + z)\hat{i} + x(y^2 - z^2)\hat{j} + 2xy(z - xy)\hat{k}$

If $\text{Div} \vec{F} = 0$ then it is solenoidal.

$$\text{Div} \vec{F} = \frac{\partial}{\partial x} y(ax^2 + z)\hat{i} + \frac{\partial}{\partial y} x(y^2 - z^2) + \frac{\partial}{\partial z} 2xy(z - xy)$$

$$\text{Div} \vec{F} = a \cdot 2xy + 2xy + 2xy$$

$$\text{Div} \vec{F} = 2axy + 4xy$$

$$2axy = -4xy$$

$$\boxed{a = -2}$$

⑪ If $\vec{F} = (x+y+1)\hat{i} + \hat{j} - (x+y)\hat{k}$ show that $\vec{F} \cdot \text{curl} \vec{F} = 0$

Given: $F = (x+y+1)\hat{i} + \hat{j} - (x+y)\hat{k}$

$$\text{curl} \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ (x+y+1) & 1 & -x-y \end{vmatrix}$$

$$= \hat{i} \left(\frac{\partial}{\partial y} (-x-y) - \frac{\partial}{\partial z} (1) \right) - \hat{j} \left(\frac{\partial}{\partial x} (-x-y) - \frac{\partial}{\partial z} (x+y+1) \right) + \hat{k} \left(\frac{\partial}{\partial x} (1) - \frac{\partial}{\partial y} (x+y+1) \right)$$

$$= \hat{i} (-1) - \hat{j} (-1) + \hat{k} (-1)$$

$$= -\hat{i} + \hat{j} - \hat{k}$$

$$\vec{F} \cdot \text{curl} \vec{F} = (x+y+1)\hat{i} + \hat{j} - (x+y)\hat{k} \cdot -\hat{i} + \hat{j} - \hat{k}$$

$$= -(x+y+1) + 1 + x+y$$

$$= -x-1-1+1+x+y$$

$$= 0 \text{ Hence proved.}$$

- (12) find the constants a and b such that $\vec{F} = (axy + z^3)\hat{i} + (3x^2 - z)\hat{j} + (bxz^2 - y)\hat{k}$ is irrotational
 wkt, if $\text{curl } \vec{F} = 0$ then it is said to be irrotational

$$\text{curl } \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ axy + z^3 & 3x^2 - z & (bxz^2 - y) \end{vmatrix}$$

$$= \hat{i} \left(\frac{\partial}{\partial y} (bxz^2 - y) - \frac{\partial}{\partial z} (3x^2 - z) \right) - \hat{j} \left(\frac{\partial}{\partial x} (bxz^2 - y) - \frac{\partial}{\partial z} (axy + z^3) \right)$$

$$+ \hat{k} \left(\frac{\partial}{\partial x} (3x^2 - z) - \frac{\partial}{\partial y} (axy + z^3) \right)$$

$$\text{curl } \vec{F} = \hat{i} (0 - 1) - (0 - 1)\hat{j} - \hat{j} (bz^2 - 3z^2) + \hat{k} (6x - ax)$$

$$bz^2 - 3z^2 = 0$$

$$6x - ax = 0$$

$$bz^2 = 3z^2$$

$$6x = ax$$

$$\boxed{b = 3}$$

$$\boxed{a = 6}$$

$\therefore$ The constants a and b are 6 & 3 respectively.

- (13) Analyse the constant a such that $\vec{F} = (axy - z^3)\hat{i} + (3x^2 - z)\hat{j} + (bxz^2 - y)\hat{k}$ is irrotational.

Given: $\vec{F} = (axy - z^3)\hat{i} + (ax^2 - 2xz^2)\hat{j} + (xz^2 - axz^2)\hat{k}$

$$\text{curl } \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ axy - z^3 & ax^2 - 2xz^2 & xz^2 - axz^2 \end{vmatrix}$$

$$= \hat{i} \left(\frac{\partial}{\partial y} (xz^2 - axz^2) - \frac{\partial}{\partial z} (ax^2 - 2xz^2) \right) - \hat{j} \left(\frac{\partial}{\partial x} (xz^2 - axz^2) - \frac{\partial}{\partial z} (axy - z^3) \right)$$

$$+ \hat{k} \left(\frac{\partial}{\partial x} (ax^2 - 2xz^2) - \frac{\partial}{\partial y} (axy - z^3) \right)$$

$$= \hat{i} (0) - \hat{j} (z^2 - az^2 + 3z^2) + \hat{k} (2ax - 4x - ax)$$

$$= 4z^2 - az^2 = 0$$

$$\boxed{a = 4}$$

$$ax = 4x$$

$$\boxed{a = 4}$$

⑭ Express vector $\vec{A} = z\hat{i} - 2x\hat{j} + y\hat{k}$ in cylindrical Coordinate System.

Given: $\vec{A} = z\hat{i} - 2x\hat{j} + y\hat{k}$

Let $\vec{F} = F_r\hat{T}_r + F_\phi\hat{T}_\phi + F_z\hat{T}_z$ be the cylindrical coordinate system — (1)

where $F_r = \vec{F} \cdot \hat{T}_r$, $F_\phi = \vec{F} \cdot \hat{T}_\phi$, $F_z = \vec{F} \cdot \hat{T}_z$

consider $F_r = \vec{F} \cdot \hat{T}_r$

$$= z\hat{i} - 2x\hat{j} + y\hat{k} \cdot \cos\phi\hat{i} + \sin\phi\hat{j}$$

$$F_r = z\cos\phi - 2r\cos\phi\sin\phi \quad \text{--- (2)}$$

$$F_\phi = \vec{F} \cdot \hat{T}_\phi$$

$$= z\hat{i} - 2x\hat{j} + y\hat{k} \cdot -\sin\phi\hat{i} + \cos\phi\hat{j}$$

$$F_\phi = -z\sin\phi - 2r\cos^2\phi \quad \text{--- (3)}$$

$$F_z = \vec{F} \cdot \hat{T}_z$$

$$= z\hat{i} - 2x\hat{j} + y\hat{k} \cdot \hat{k}$$

$$F_z = r\sin\phi \quad \text{--- (4)}$$

Substituting eqⁿ (2) (3) & (4) in (1)

$$\vec{F} = (z\cos\phi - 2r\cos\phi\sin\phi)\hat{T}_r + (-z\sin\phi - 2r\cos^2\phi)\hat{T}_\phi + r\sin\phi\hat{T}_z$$

⑮ Show that spherical coordinate system is orthogonal.

We have to show that

$$\hat{e}_r \cdot \hat{e}_\theta = \hat{e}_\theta \cdot \hat{e}_\phi = \hat{e}_\phi \cdot \hat{e}_r = 0$$

consider,

$$\hat{e}_r \cdot \hat{e}_\theta = (\sin\theta\cos\phi\hat{i} + \sin\theta\sin\phi\hat{j} + \cos\theta\hat{k}) \cdot (\cos\theta\cos\phi\hat{i} + \cos\theta\sin\phi\hat{j} - \sin\theta\hat{k})$$

$$= \sin\theta\cos\theta\cos^2\phi + \sin\theta\cos\theta\sin^2\phi - \sin\theta\cos\theta$$

$$= \sin\theta\cos\theta(1) - \sin\theta\cos\theta$$

$$= 0$$

$$\hat{e}_\theta \cdot \hat{e}_\phi = (\cos\theta\cos\phi\hat{i} + \cos\theta\sin\phi\hat{j} - \sin\theta\hat{k}) \cdot (-\sin\phi\hat{i} + \cos\phi\hat{j})$$

$$= -\cos\theta\cos\phi\sin\phi + \cos\theta\cos\phi\sin\phi$$

$$= 0$$

$$\begin{aligned}\hat{e}_\phi \cdot \hat{e}_r &= (-\sin\phi \hat{i} + \cos\phi \hat{j}) \cdot (\sin\theta \cos\phi \hat{i} + \sin\theta \sin\phi \hat{j} + \cos\theta \hat{k}) \\ &= -\sin\phi \sin\theta \cos\phi + \cos\phi \sin\theta \sin\phi \\ &= \underline{\underline{0}}\end{aligned}$$

Hence spherical coordinate system is orthogonal.

(16) Show that cylindrical coordinate system is orthogonal.

we have to show that

$$\hat{T}_r \cdot \hat{T}_\phi = \hat{T}_\phi \cdot \hat{T}_z = \hat{T}_z \cdot \hat{T}_r = 0$$

Consider

$$\begin{aligned}\hat{T}_r \cdot \hat{T}_\phi &= (\cos\phi \hat{i} + \sin\phi \hat{j}) \cdot (-\sin\phi \hat{i} + \cos\phi \hat{j}) \\ &= -\cos\phi \sin\phi + \sin\phi \cos\phi \\ &= 0\end{aligned}$$

$$\begin{aligned}\hat{T}_\phi \cdot \hat{T}_z &= (-\sin\phi \hat{i} + \cos\phi \hat{j}) \cdot \hat{k} \\ &= 0\hat{i} + 0\hat{j} + 0\hat{k} \\ &= 0\end{aligned}$$

$$\begin{aligned}\hat{T}_z \cdot \hat{T}_r &= \hat{k} \cdot (\cos\phi \hat{i} + \sin\phi \hat{j}) \\ &= 0\hat{i} + 0\hat{j} + 0\hat{k} \\ &= 0\end{aligned}$$

Hence cylindrical coordinate system is orthogonal.

(17) Express $\vec{A} = z\hat{i} - 2x\hat{j} + y\hat{k}$ in spherical coordinate system.

Let $\vec{F} = F_r \hat{e}_r + F_\theta \hat{e}_\theta + F_\phi \hat{e}_\phi$ be the required spherical coordinate system. — (1)

$$F_r = \vec{F} \cdot \hat{e}_r, \quad F_\theta = \vec{F} \cdot \hat{e}_\theta, \quad F_\phi = \vec{F} \cdot \hat{e}_\phi$$

consider,

$$F_r = \vec{F} \cdot \hat{e}_r$$

$$= z\hat{i} - 2x\hat{j} + y\hat{k} \cdot \sin\theta \cos\phi \hat{i} + \sin\theta \sin\phi \hat{j} + \cos\theta \hat{k}$$

$$= z \sin\theta \cos\phi - 2x \sin\theta \sin\phi + y \cos\theta$$

$$= r \cos\theta \sin\theta \cos\phi - 2r \sin\theta \cos\phi \sin\theta \sin\phi + r \sin\theta \sin\phi \cos\theta$$

$$F_r = r \sin\theta (\cos\theta \cos\phi - 2 \cos\phi \sin\theta \sin\phi + \sin\phi \cos\theta)$$

— (2)

$$\begin{aligned}x &= r \sin\theta \cos\phi \\ y &= r \sin\theta \sin\phi \\ z &= r \cos\theta\end{aligned}$$

$$F_\theta = \vec{F} \cdot \hat{e}_\theta$$

$$= (r \cos \theta \hat{i} - 2r \sin \theta \cos \phi \hat{j} + r \sin \theta \sin \phi \hat{k}) \cdot \cos \phi \cos \theta \hat{i} + \cos \theta \sin \phi \hat{j} - \sin \theta \hat{k}$$

$$= r \cos^2 \theta \cos \phi - 2r \cos \phi \sin \theta \cos \theta \sin \phi + r \sin \theta \sin \phi \sin \theta$$

$$F_\theta = r (\cos^2 \theta \cos \phi - 2 \cos \phi \sin \theta \cos \theta \sin \phi + \sin^2 \theta \sin \phi) \quad \text{--- (3)}$$

$$F_\phi = \vec{F} \cdot \hat{e}_\phi$$

$$= (r \cos \theta \hat{i} - 2r \sin \theta \cos \phi \hat{j} + r \sin \theta \sin \phi \hat{k}) \cdot -\sin \phi \hat{i} + \cos \phi \hat{j}$$

$$= -r \cos \theta \sin \phi - 2r \sin \theta \cos^2 \phi$$

$$F_\phi = -r (\cos \theta \sin \phi + 2 \sin \theta \cos^2 \phi) \quad \text{--- (4)}$$

Substitute (2), (3) & (4) in (1)

$$\vec{F} = r \sin \theta (\cos \theta \cos \phi - 2 \cos \phi \sin \theta \sin \phi + \sin \phi \cos \theta) \hat{e}_r +$$

$$r (\cos^2 \theta \cos \phi - 2 \sin \theta \cos \phi - \sin^2 \theta \sin \phi) \hat{e}_\theta +$$

$$-r (\cos \theta \sin \phi + 2 \sin \theta \cos^2 \phi) \hat{e}_\phi$$